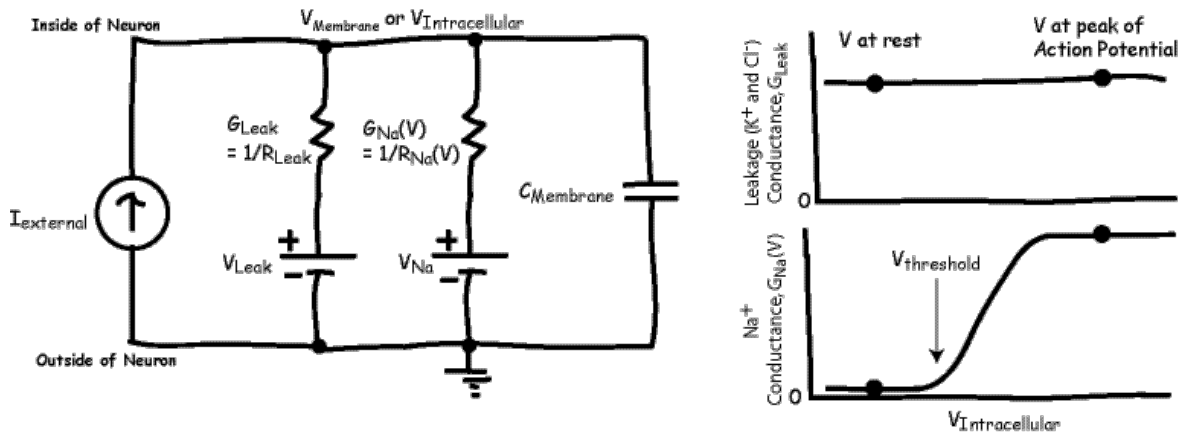


This handout pertains to the operation of a neuron. The neuron does three things. First, it integrates inputs, in the form of both positive and negative currents, from select neighboring cells. Second, it generates a pulse if the voltage caused by the sum of those currents exceeds a threshold value. Third, the pulse is used as a signal to trigger injection of current to select neighboring cells. In this way, the neuron functions as a logic element - the correct pattern of input, which can come from sensing the environment, is turned into an output, which can drive further processing or a motor task.

The kernel of pulse generation may be understood in terms of a minimal neuron that has a steady-state potential in the absence of input and a voltage-dependent Na^+ -ion conductance that turns on if a voltage threshold is crossed. This leads to a form of bistability that will explain the rising edge of a neuronal pulse (action potential) - which lasts 0.1 ms - and the rising edge of a cardiac pulse as well. We ignore the slow recovery phase for the moment, which is ~1 ms or 10-times the rise time for neurons and 100 ms or longer for cardiac cells.



For the circuit above, and noting that $I = GV$ where $G \equiv 1/R$, we can use Kirchoff's node law to write

$$G_{\text{Leak}} [V_m - V_{\text{Leak}}] + G_{\text{Na}}(V) [V_m - V_{\text{Na}}] + C_m \frac{dV_m}{dt} + I_{\text{external}} = 0$$

where

$$I_{\text{external}} = \sum_{\text{all synapses}} I_{\text{synaptic}} + I_{\text{applied}}$$

In steady state, the capacitive current is zero, and:

$$G_{\text{Leak}} [V_m - V_{\text{Leak}}] + G_{\text{Na}}(V) [V_m - V_{\text{Na}}] + I_{\text{external}} = 0.$$

There are two limits:

1. The potential is below threshold, so $G_{\text{Na}}(V) = 0$ and:

$$G_{\text{Leak}} [V_m - V_{\text{Leak}}] + I_{\text{external}} = 0.$$

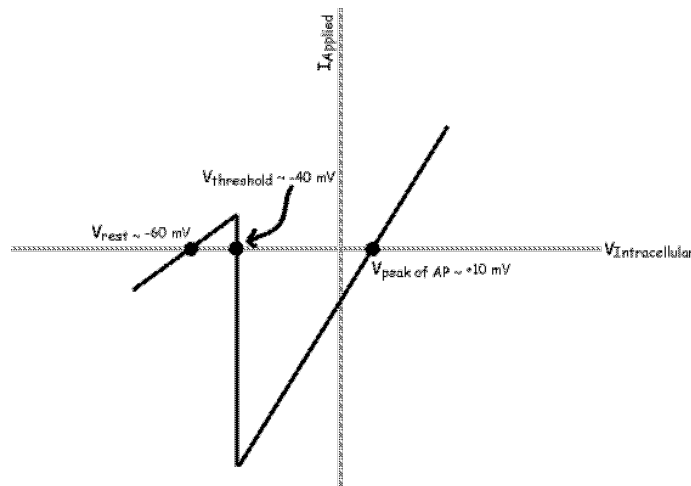
A little rearranging gives:

$$V_m = V_{\text{Leak}} - \frac{I_{\text{external}}}{G_{\text{Leak}}}.$$

The input conductance is just

$$\frac{\Delta I_{\text{applied}}}{\Delta V_m} = G_{\text{Leak}}.$$

When there are no input currents, $I_{\text{external}} = 0$ and $V_m = V_{\text{Leak}}$. We refer to this value of V_m as the resting potential, V_{rest} .



2. When the potential is above threshold, $G_{\text{Na}}(V) = G_{\text{Na}}^{\text{max}}$ and:

$$G_{\text{Leak}} [V_m - V_{\text{Leak}}] + G_{\text{Na}}^{\text{max}} [V_m - V_{\text{Na}}] + I_{\text{external}} = 0.$$

A little rearranging gives:

$$V_m = \frac{G_{\text{Leak}} V_{\text{Leak}} + G_{\text{Na}}^{\text{max}} V_{\text{Na}}}{G_{\text{Leak}} + G_{\text{Na}}^{\text{max}}} - \frac{I_{\text{external}}}{G_{\text{Leak}} + G_{\text{Na}}^{\text{max}}}.$$

The input conductance is now increased to

$$\frac{\Delta I_{\text{applied}}}{\Delta V_m} = G_{\text{Leak}} + G_{\text{Na}}^{\text{max}}.$$

When there are no input currents, $V_m = \frac{G_{\text{Leak}} V_{\text{Leak}} + G_{\text{Na}}^{\text{max}} V_{\text{Na}}}{G_{\text{Leak}} + G_{\text{Na}}^{\text{max}}}$ is the potential at the top of the action potential. We refer to this value as $V_{\text{peak of AP}}$.